



SOME RESULTS ON POHLKE'S TYPE ELLIPSES

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Abstract. We give here formulae for determining the Pohlke's ellipse and the secondary Pohlke's ellipse of a triad of segments in a plane. Then we apply these results to find an explicit expression of the secondary Pohlke's projection introduced in [6].

1. INTRODUCTION

Let OP_1, OP_2, OP_3 be three non-parallel segments in a plane ω and let $\mathcal{E}_{P_1, P_2}, \mathcal{E}_{P_2, P_3}$ and \mathcal{E}_{P_3, P_1} be the concentric ellipses defined by the three pairs of conjugate semi-diameters $(OP_1, OP_2), (OP_2, OP_3)$ and (OP_3, OP_1) respectively. It was proved in [8] and then in [6] that there are at most two distinct ellipses with center O circumscribing $\mathcal{E}_{P_1, P_2}, \mathcal{E}_{P_2, P_3}, \mathcal{E}_{P_3, P_1}$.

The first, which we denote by \mathcal{E}_p , is the Pohlke's ellipse (see also [2], [3]). It is determined by the requirement that there exists a sphere S with center O , three points $Q_1, Q_2, Q_3 \in S$ and a parallel projection $\Pi : \mathbb{E}^3 \rightarrow \omega$ (i.e., a Pohlke's projection) such that:

- (1) $\Pi(OQ_i) = OP_i \quad (1 \leq i \leq 3),$
- (2) $OQ_1 \perp OQ_2, \quad OQ_2 \perp OQ_3, \quad OQ_3 \perp OQ_1.$

With S, Π as above, the Pohlke's ellipse \mathcal{E}_p for OP_1, OP_2, OP_3 is the contour of the projection onto ω of the sphere S , i.e.

- (3) $\mathcal{E}_p \stackrel{\text{def}}{=} \Pi(S \cap \pi),$

where π the plane through O and perpendicular to the direction of Π . Existence and uniqueness of such an ellipse are guaranteed by Pohlke's theorem of oblique axonometry [7]. See [1], [4] for an analytic proof. The other, which we denote by \mathcal{E}_s , is the *secondary* Pohlke's ellipse:

Definition 1.1. A *secondary Pohlke's ellipse* for the triad of segments OP_1, OP_2, OP_3 is an ellipse $\mathcal{E}_s \neq \mathcal{E}_p$, centered at O , which circumscribes the three ellipses $\mathcal{E}_{P_1, P_2}, \mathcal{E}_{P_2, P_3}, \mathcal{E}_{P_3, P_1}$.

By the results of [6] (Theorem 2.1, **(a)** \Leftrightarrow **(b)**) a secondary Pohlke's ellipse \mathcal{E}_s is determined by the requirement that there exists a sphere \tilde{S} with center O , three points $R_1, R_2, R_3 \in \tilde{S}$ and a parallel projection $\tilde{\Pi} : \mathbb{E}^3 \rightarrow \omega$ (i.e., a secondary Pohlke's projection) such that:

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$$\begin{aligned}
(4) \quad & \tilde{\Pi}(OR_i) = OP_i \quad (1 \leq i \leq 3), \\
(5) \quad & OR_1 \perp OR_2, \quad OR_2 \perp OR_3 \quad \text{and} \quad OR_3 \perp OR_1', \\
(6) \quad & R_i \notin \tilde{\pi} \quad (\text{i.e., } R_i \neq R_i') \quad (1 \leq i \leq 3)
\end{aligned}$$

where $\tilde{\pi}$ is the plane through O and perpendicular to the direction of $\tilde{\Pi}$; the point R_i' is symmetric to R_i with respect to $\tilde{\pi}$. With \tilde{S} , $\tilde{\Pi}$ and $\tilde{\pi}$ as above, we have

$$(7) \quad \mathcal{E}_S = \tilde{\Pi}(\tilde{S} \cap \tilde{\pi}).$$

See also [8] for an alternative approach.

Unlike the Pohlke's ellipse \mathcal{E}_P , which exists even if two of the segments OP_1, OP_2, OP_3 are parallel (see Section 2), the secondary Pohlke's ellipse \mathcal{E}_S does not always exist. More precisely, from [6] (Theorem 2.1, equivalence (a), (b) \Leftrightarrow (c)) we also know that:

Theorem 1.1. *Suppose the segments OP_1, OP_2, OP_3 are non-parallel. Then there exists a secondary Pohlke's ellipse \mathcal{E}_S if and only if*

$$(8) \quad a\overrightarrow{OP_1} + b\overrightarrow{OP_2} + c\overrightarrow{OP_3} = 0,$$

with $a, b, c \neq 0$ such that

$$(9) \quad G(a, b, c) \stackrel{\text{def}}{=} a^4 + b^4 + c^4 - 2a^2b^2 - 2a^2c^2 - 2b^2c^2 > 0.$$

Further, if \mathcal{E}_S exists then \mathcal{E}_S is unique.

The preceding definitions of \mathcal{E}_P and \mathcal{E}_S are not invariant under affine transformations of the euclidean space \mathbb{E}^3 due to the requirement that S, \tilde{S} be spheres and also for the orthogonality conditions in (2) and (5), (6). However, we show here that under affine transformation of the plane ω the Pohlke's ellipse of the segments OP_1, OP_2, OP_3 transforms into the Pohlke's ellipse of the transformed segments and the same is true for the secondary Pohlke's ellipse when it exists, i.e., if (8)-(9) holds.

Notation 1.1. *For greater clarity we will often write*

$$(10) \quad \mathcal{E}_P(O, P_1, P_2, P_3) \quad \text{and} \quad \mathcal{E}_S(O, P_1, P_2, P_3),$$

instead of \mathcal{E}_P and \mathcal{E}_S , to make explicit the triad of segments from which a given Pohlke's ellipse or a given secondary Pohlke's ellipse refers.

In this article we will demonstrate a number of facts about Pohlke's ellipses and secondary Pohlke's ellipses which we can summarize as follows:

- In Section 3, assuming OP_1, OP_2, OP_3 are not all parallel, we determine a pair of conjugate semi-diameters of the Pohlke's ellipse \mathcal{E}_P and then we apply this result to prove that if $\Psi : \omega \rightarrow \omega$ is any affine transformation then

$$(11) \quad \Psi(\mathcal{E}_P(O, P_1, P_2, P_3)) = \mathcal{E}_P(\Psi(O), \Psi(P_1), \Psi(P_2), \Psi(P_3)).$$

- In Section 4, assuming OP_1, OP_2, OP_3 are non-parallel and (8)-(9) holds, we demonstrate similar results for the secondary Pohlke's ellipse \mathcal{E}_S . In particular, noting that $\mathcal{E}_S(\Psi(O), \Psi(P_1), \Psi(P_2), \Psi(P_3))$

exists because condition (8)-(9) is invariant under affine transformations of the plane ω , we prove that

$$(12) \quad \Psi(\mathcal{E}_S(O, P_1, P_2, P_3)) = \mathcal{E}_S(\Psi(O), \Psi(P_1), \Psi(P_2), \Psi(P_3)).$$

Using (11) and (12) we also show that

$$(13) \quad \text{area}(\mathcal{E}_P) < \text{area}(\mathcal{E}_S),$$

because it holds if two of the segments OP_1, OP_2, OP_3 are perpendicular and equal.

- In Section 5, assuming OP_1, OP_2, OP_3 are non-parallel and (8)-(9) holds, we show that

$$(14) \quad \mathcal{E}_S(O, P_1, P_2, P_3) = \mathcal{E}_P(O, P_1, P_2, X_3),$$

where the point X_3 is such that

$$(15) \quad \pm \overrightarrow{OX_3} = \frac{a(a^2 - b^2 - c^2)}{c\sqrt{G}} \overrightarrow{OP_1} + \frac{b(a^2 - b^2 + c^2)}{c\sqrt{G}} \overrightarrow{OP_2},$$

with $G = G(a, b, c)$ the quantity defined by (9).

Similarly we can prove that $\mathcal{E}_S(O, P_1, P_2, P_3) = \mathcal{E}_P(O, X_1, P_2, P_3) = \mathcal{E}_P(O, P_1, X_2, P_3)$ by appropriately defining X_1, X_2 respectively.

- In Section 5.1, applying (14) and the formulae of [4] for Pohlke's projection, we finally give a procedure to explicitly determine the secondary Pohlke's projection $\tilde{\Pi}$ and the points R_1, R_2, R_3 such that conditions (4), (5), (6) hold.

2. PRELIMINARIES

In this section we suppose OP_1, OP_2, OP_3 are not all parallel.¹ To determine the Pohlke's ellipse \mathcal{E}_P we resume some of the arguments introduced in [4], [5]. Namely, we adopt a system of coordinate axes x, y, z such that ω is the plane $z = 0$,

$$(16) \quad O = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}, \quad P_1 = \begin{pmatrix} x_1 \\ y_1 \\ 0 \end{pmatrix}, \quad P_2 = \begin{pmatrix} x_2 \\ y_2 \\ 0 \end{pmatrix}, \quad P_3 = \begin{pmatrix} x_3 \\ y_3 \\ 0 \end{pmatrix}$$

and we also consider the matrix

$$(17) \quad A = \begin{pmatrix} x_1 & x_2 & x_3 \\ y_1 & y_2 & y_3 \\ 0 & 0 & 0 \end{pmatrix} = \begin{pmatrix} A_1 \\ A_2 \\ 0 \end{pmatrix}.$$

The rows A_1, A_2 are linearly independent (i.e., $\text{car}(A) = 2$) because OP_1, OP_2, OP_3 are not all parallel. Hence can we define:

$$(18) \quad \gamma \stackrel{\text{def}}{=} \arccos \left(\frac{A_1 \cdot A_2}{\|A_1\| \|A_2\|} \right), \quad \lambda \stackrel{\text{def}}{=} \frac{\|A_1\|}{\|A_2\|}.$$

¹ If two of the segments OP_1, OP_2, OP_3 are parallel (or if one of them vanishes) we can still say that \mathcal{E}_P circumscribes \mathcal{E}_{P_1, P_2} , \mathcal{E}_{P_2, P_3} and \mathcal{E}_{P_3, P_1} but we need to introduce *degenerate* ellipses as in [1, pp. 372-373]. For instance, if $OP_1 \parallel OP_2$ then we set $\mathcal{E}_{P_1, P_2} = MN$, where MN is the segment parallel to OP_1, OP_2 such that $O = (M + N)/2$ and $|ON|^2 = |OP_1|^2 + |OP_2|^2$. In this case we say that \mathcal{E}_P circumscribes \mathcal{E}_{P_1, P_2} if $M, N \in \mathcal{E}_P$. We also say that \mathcal{E}_P is tangent to \mathcal{E}_{P_1, P_2} at M, N . See the Definitions 3.1, 3.3 of [6].

Noting that $0 < \gamma < \pi$ and $\lambda > 0$, we can also introduce the quantities:

$$(19) \quad \eta \stackrel{\text{def}}{=} \frac{\lambda^2 + 1 + \sqrt{(\lambda^2 + 1)^2 - 4\lambda^2 \sin^2 \gamma}}{2\lambda^2 \sin^2 \gamma}$$

and then²

$$(20) \quad (\alpha, \beta) \stackrel{\text{def}}{=} \pm \left(\sqrt{\eta \lambda^2 - 1}, \operatorname{sgn}(\cos \gamma) \sqrt{\eta - 1} \right),$$

where

$$(21) \quad \operatorname{sgn}(t) \stackrel{\text{def}}{=} \begin{cases} 1 & \text{if } t \geq 0 \\ -1 & \text{if } t < 0 \end{cases}.$$

Finally, we define the parallel projection $\Pi : \mathbb{E}^3 \rightarrow \omega$ as

$$(22) \quad \Pi \begin{pmatrix} x \\ y \\ z \end{pmatrix} \stackrel{\text{def}}{=} \begin{pmatrix} x + \alpha z \\ y + \beta z \\ 0 \end{pmatrix}.$$

The Pohlke's ellipse $\mathcal{E}_{\mathbb{P}}$ of OP_1, OP_2, OP_3 is then the contour of the projection into the plane ω of the sphere S with center O and radius

$$(23) \quad \rho \stackrel{\text{def}}{=} \frac{\|A_1\|}{\lambda \sqrt{\eta}} = \frac{\|A_2\|}{\sqrt{\eta}}.$$

Namely, $\mathcal{E}_{\mathbb{P}} = \Pi(S \cap \pi)$ where π is the plane $\pi : \alpha x + \beta y - z = 0$.

Remark 2.1. *It is worthwhile noting that $\mathcal{E}_{\mathbb{P}}$ uniquely determines the sphere S centered at O , because the radius of S must be equal to the semi-minor axis of $\mathcal{E}_{\mathbb{P}}$. Furthermore, the Pohlke's projection $\Pi : \mathbb{E}^3 \rightarrow \omega$ is determined up to symmetry with respect to the plane ω . Namely, if the semi-axes of $\mathcal{E}_{\mathbb{P}}$ are given by two perpendicular segments $OV, OW \subset \omega$ such that*

$$(24) \quad 0 < |OV| \leq |OW| \quad \text{and} \quad W = \begin{pmatrix} p \\ q \\ 0 \end{pmatrix},$$

then the sphere S has radius $\rho = |OV|$ and the direction of projection is given by the column vector

$$(25) \quad \vec{n} = \begin{pmatrix} \delta p \\ \delta q \\ \pm 1 \end{pmatrix} \quad \text{with} \quad \delta = \sqrt{\frac{p^2 + q^2 - \rho^2}{\rho^2(p^2 + q^2)}}.$$

If $\delta = 0$ then $\mathcal{E}_{\mathbb{P}}$ is a circle and we have only the orthogonal projection. Conversely, if $\delta > 0$ the two possible signs of the last component of \vec{n} correspond to two distinct projections which are symmetric with respect to the plane ω . Indeed, if $\bar{\Pi} : \mathbb{E}^3 \rightarrow \omega$ is defined by

$$(26) \quad \bar{\Pi}(P) = \Pi(\bar{P}) \quad \text{where } \bar{P} \text{ is symmetric to } P \text{ with respect to } \omega,$$

² We note that $\eta, \eta \lambda^2 \geq 1$. Indeed from (19) we easily have:

$$\eta(\lambda, \gamma) \geq \eta(\gamma, \frac{\pi}{2}) = \frac{\lambda^2 + 1 + |\lambda^2 - 1|}{2\lambda^2} = \begin{cases} 1/\lambda^2 & \text{if } 0 < \lambda \leq 1 \\ 1 & \text{if } \lambda \geq 1 \end{cases}.$$

then (1) and (2) are verified with $\bar{\Pi}$ instead of Π and $\bar{Q}_1, \bar{Q}_2, \bar{Q}_3$ instead of Q_1, Q_2, Q_3 respectively. Given two projections $\Pi_1, \Pi_2 : \mathbb{E}^3 \rightarrow \omega$, we will later write that

$$(27) \quad \Pi_1 \sim \Pi_2 \quad \Leftrightarrow \quad \Pi_1 = \Pi_2 \quad \text{or} \quad \Pi_1 = \bar{\Pi}_2.$$

The same considerations apply to the secondary Pohlke's ellipse \mathcal{E}_S (and to the corresponding sphere \tilde{S} and projection $\tilde{\Pi}$) when (8)-(9) holds. \square

Remark 2.2. Looking at (19) - (22), it is worth noting that the Pohlke's projection Π depends only on the quantities γ, λ which we have defined in (18). Taking into account (23), it is also immediate that:

\mathcal{E}_P remains unchanged if $\|A_1\|, \|A_2\|$ and $A_1 \cdot A_2$ do not vary.

Using (25) and the expressions (28) of the lengths of the semi-axes of \mathcal{E}_P , it is possible to prove that the converse of this last statement is also true. \square

3. THE POHLKE'S ELLIPSE \mathcal{E}_P

As in the previous section, we suppose that OP_1, OP_2, OP_3 are not all parallel and we use a system of coordinate axes x, y, z such that ω is the plane $z = 0$ and (16) holds.

Lemma 3.1. The lengths σ_-, σ_+ of the semi-axes of the Pohlke's ellipse \mathcal{E}_P are given by

$$(28) \quad (\sigma_{\pm})^2 = \frac{\|A_1\|^2 + \|A_2\|^2 \pm \sqrt{(\|A_1\|^2 + \|A_2\|^2)^2 - 4\|A_1 \wedge A_2\|^2}}{2}.$$

Proof. Since $\mathcal{E}_P = \Pi(S \cap \pi)$, it is clear that $\sigma_- = \rho$ where ρ is the radius of S given by (23). From (22) we can also see that $\sigma_+ = \rho\sqrt{1 + \alpha^2 + \beta^2}$ because the direction of projection is given by the column vector

$$(29) \quad \vec{u} = \begin{pmatrix} -\alpha \\ -\beta \\ 1 \end{pmatrix}.$$

Taking account (19) and (23), we have

$$(30) \quad \sigma_-^2 = \frac{\|A_2\|^2}{\eta} = \|A_2\|^2 \frac{\lambda^2 + 1 - \sqrt{(\lambda^2 + 1)^2 - 4\lambda^2 \sin^2 \gamma}}{2}.$$

While, by (19), (20) and (23) we obtain

$$(31) \quad \begin{aligned} \sigma_+^2 &= \rho^2(1 + \alpha^2 + \beta^2) \\ &= \frac{\|A_2\|^2}{\eta} (\eta\lambda^2 + \eta - 1) = \|A_2\|^2 (\lambda^2 + 1 - \eta^{-1}) \\ &= \|A_2\|^2 \frac{\lambda^2 + 1 + \sqrt{(\lambda^2 + 1)^2 - 4\lambda^2 \sin^2 \gamma}}{2}. \end{aligned}$$

Using the definitions (18) of γ and λ and noting that

$$(32) \quad \|A_1\| \|A_2\| \sin \gamma = \|A_1 \wedge A_2\|,$$

we obtain (28). \square

Remark 3.1. σ_-, σ_+ are also the lengths of the semi-axes of the ellipse \mathcal{E} defined by the pair of conjugate semi-diameters (OA_1, OA_2) .³ In fact, by Apollonius's theorems on conjugate diameters, the lengths a, b of these semi-axes satisfy the system

$$(33) \quad a^2 + b^2 = \|A_1\|^2 + \|A_2\|^2, \quad ab = \|A_1 \wedge A_2\|.$$

Thus we immediately find

$$(34) \quad a^2, b^2 = \frac{\|A_1\|^2 + \|A_2\|^2 \pm \sqrt{(\|A_1\|^2 + \|A_2\|^2)^2 - 4\|A_1 \wedge A_2\|^2}}{2},$$

i.e., formula (28). □

Remark 3.2. Noting (17), from (28) we get

$$(35) \quad \sigma_-^2 + \sigma_+^2 = \|A_1\|^2 + \|A_2\|^2 = |OP_1|^2 + |OP_2|^2 + |OP_3|^2.$$

See also [2, Main Theorem 3.1] for an alternative proof of (35). □

Lemma 3.2. If one of the segments OP_1, OP_2, OP_3 vanishes then $\mathcal{E}_{\mathfrak{p}}$ is the ellipse determined by the pair of conjugate semi-diameters given by the other two segments.

Proof. Suppose OP_3 vanishes. Then we must prove that $\mathcal{E}_{\mathfrak{p}} = \mathcal{E}_{P_1, P_2}$. Namely, the Pohlke's ellipse $\mathcal{E}_{\mathfrak{p}}$ is determined by the pair of conjugate semi-diameters (OP_1, OP_2) . We can argue in various ways:

- Since $P_3 = O$, in (1) the direction of the projection Π is given by the segments OQ_3 . By the orthogonality conditions (2) this means that $Q_1, Q_2 \in \pi$. Hence, it follows that

$$(36) \quad \mathcal{E}_{P_1, P_2} = \Pi(S \cap \pi) = \mathcal{E}_{\mathfrak{p}}.$$

- Since $\mathcal{E}_{\mathfrak{p}}$ and \mathcal{E}_{P_1, P_2} are concentric and tangent at some point P , there exists $P', P'' \neq O$, with $OP' \parallel OP''$ and $OP' \supset OP''$, such that $\mathcal{E}_{\mathfrak{p}}$ and \mathcal{E}_{P_1, P_2} are determined by the pairs of conjugate semi-diameters (OP, OP') and (OP, OP'') respectively. By Apollonius's theorem on conjugate semi-diameters and Remark 3.2 we have

$$(37) \quad |OP|^2 + |OP'|^2 = |OP_1|^2 + |OP_2|^2 = |OP|^2 + |OP''|^2.$$

This gives $|OP'| = |OP''|$ and we deduce that $\mathcal{E}_{\mathfrak{p}} = \mathcal{E}_{P_1, P_2}$ because they are determined by the same pair of conjugate semi-diameters.

- Lemma 3.2 is immediate if we also consider the degenerate ellipses.¹ Indeed, if $OP_3 = O$ then $\mathcal{E}_{P_1, P_3} = \mathcal{E}_{P_1, O} = P_1P'_1$ and $\mathcal{E}_{P_2, P_3} = \mathcal{E}_{P_2, O} = P_2P'_2$, where the points P'_1, P'_2 are symmetric to P_1, P_2 respectively, with respect to O . It follows that $P_1, P_2 \in \mathcal{E}_{\mathfrak{p}}$ and that the ellipses $\mathcal{E}_{\mathfrak{p}}$ and \mathcal{E}_{P_1, P_2} are tangent at P_1 and P_2 . Hence $\mathcal{E}_{\mathfrak{p}} = \mathcal{E}_{P_1, P_2}$. See also [6, Section 3].

Having proved Lemma 3.2, we now suppose that the segments OP_1, OP_2, OP_3 do not vanish. We begin with a special case:

³ Here, with a slight abuse of notation, we use A_1, A_2 to indicate two points with the same coordinates of the rows A_1, A_2 of the matrix A defined in (17).

Lemma 3.3. *Let us suppose that*

$$(38) \quad U_1 = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \quad U_2 = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}, \quad U_3 = \begin{pmatrix} h \\ k \\ 0 \end{pmatrix},$$

with h, k not both zero (i.e., $U_3 \neq O$). Then the semi-axes of the Pohlke's ellipse $\mathcal{E}_P(O, U_1, U_2, U_3)$ are the segments $O\Sigma_-$ and $O\Sigma_+$ with

$$(39) \quad \Sigma_- = \frac{\pm 1}{\sqrt{h^2 + k^2}} \begin{pmatrix} k \\ -h \\ 0 \end{pmatrix}, \quad \Sigma_+ = \pm \sqrt{\frac{1 + h^2 + k^2}{h^2 + k^2}} \begin{pmatrix} h \\ k \\ 0 \end{pmatrix}.$$

Proof. According to (16), (17) we set

$$(40) \quad A = \begin{pmatrix} 1 & 0 & h \\ 0 & 1 & k \\ 0 & 0 & 0 \end{pmatrix}$$

and then we follow the scheme from (18) to (23). We have

$$(41) \quad \cos \gamma = \frac{hk}{\sqrt{1+h^2}\sqrt{1+k^2}}, \quad \lambda = \frac{\sqrt{1+h^2}}{\sqrt{1+k^2}}.$$

From this we get $\eta = 1 + k^2$, $\rho = \|A_2\| \eta^{-1/2} = 1$ and

$$(42) \quad (\alpha, \beta) = \pm(|h|, \operatorname{sgn}(hk)|k|) = \pm(h, k).$$

It follows that the lengths of the semi-axes are

$$(43) \quad \sigma_- = 1 \quad \text{and} \quad \sigma_+ = \sqrt{1 + h^2 + k^2}.$$

Moreover, the direction of projection onto the image plane ω is given by the

nonzero vector $\vec{v} = \begin{pmatrix} -h \\ -k \\ 1 \end{pmatrix}$ or $\begin{pmatrix} h \\ k \\ 1 \end{pmatrix}$. This means that

$$(44) \quad O\Sigma_- \parallel \begin{pmatrix} h \\ -k \\ 0 \end{pmatrix}, \quad O\Sigma_+ \parallel \begin{pmatrix} h \\ k \\ 0 \end{pmatrix}$$

and then we can easily derive the expressions (39) for Σ_- and Σ_+ . \square

Remark 3.3. *It is easy to find the Pohlke's projection corresponding to U_1, U_2, U_3 directly. Indeed, in view of (38), \mathcal{E}_{U_1, U_2} is a circle with center O and radius $\rho = 1$. Hence, $\mathcal{E}_P(O, U_1, U_2, U_3)$ must have semi-minor axis $\sigma_- = 1$. This means that S has radius $\rho = 1$ and that the conditions (1), (2) are satisfied (with $P_i = U_i$, $1 \leq i \leq 3$) taking $Q_1 = U_1$, $Q_2 = U_2$,*

$$(45) \quad Q_3 = \pm \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$$

and the direction of the projection Π parallel to the segment Q_3U_3 , i.e., the vector \vec{v} above. See [6, Section 4] for more details. \square

We are now in position to obtain the expressions of the conjugate semi-diameters of \mathcal{E}_P in the general case:

Lemma 3.4. *Suppose $OP_1 \nparallel OP_2$ and*

$$(46) \quad \overrightarrow{OP_3} = h\overrightarrow{OP_1} + k\overrightarrow{OP_2},$$

with h, k not both zero (i.e., $OP_3 \neq O$). Then the segments OV, OW with

$$(47) \quad \begin{aligned} \overrightarrow{OV} &= \pm \frac{k\overrightarrow{OP_1} - h\overrightarrow{OP_2}}{\sqrt{h^2 + k^2}} \quad \text{and} \\ \overrightarrow{OW} &= \pm \sqrt{\frac{1 + h^2 + k^2}{h^2 + k^2}} \left(h\overrightarrow{OP_1} + k\overrightarrow{OP_2} \right) \end{aligned}$$

are conjugate semi-diameters of the Pohlke's ellipse \mathcal{E}_P .

Proof. Noting that $OV \nparallel OW$, it is enough to show that $\mathcal{E}_P(O, P_1, P_2, P_3)$ coincides with the Pohlke's ellipse $\mathcal{E}_P(O, V, W, O)$, where the third segment vanishes. Indeed, by Lemma 3.2, OV and OW are conjugate semi-diameters of $\mathcal{E}_P(O, V, W, O)$. To prove this fact, we consider the matrix \mathcal{A} given by the coordinates of the points V, W and O . Namely, we set

$$(48) \quad \mathcal{A} = \begin{pmatrix} \frac{1}{\sqrt{h^2+k^2}}(kx_1 - hx_2) & \sqrt{\frac{1+h^2+k^2}{h^2+k^2}}(hx_1 + kx_2) & 0 \\ \frac{1}{\sqrt{h^2+k^2}}(ky_1 - hy_2) & \sqrt{\frac{1+h^2+k^2}{h^2+k^2}}(hy_1 + ky_2) & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

where, for simplicity, in (47) we always choose the sign " + ". Then we evaluate the norms and the scalar product of the rows $\mathcal{A}_1, \mathcal{A}_2$ of \mathcal{A} . By (46) we have $x_3 = hx_1 + kx_2$ and $y_3 = hy_1 + ky_2$. Thus, we obtain:

$$(49) \quad \begin{aligned} \|\mathcal{A}_1\|^2 &= \frac{(kx_1 - hx_2)^2}{h^2 + k^2} + \frac{1 + h^2 + k^2}{h^2 + k^2}(hx_1 + kx_2)^2 \\ &= \frac{(hx_1 + kx_2)^2 + (kx_1 - hx_2)^2}{h^2 + k^2} + (hx_1 + kx_2)^2 \\ &= x_1^2 + x_2^2 + x_3^2 = \|\mathcal{A}_1\|^2, \end{aligned}$$

and in the same way we can show that $\|\mathcal{A}_2\|^2 = \|\mathcal{A}_2\|^2$.

Further, we consider the scalar product $\mathcal{A}_1 \cdot \mathcal{A}_2$. We have:

$$\begin{aligned} \mathcal{A}_1 \cdot \mathcal{A}_2 &= \frac{(kx_1 - hx_2)(ky_1 - hy_2)}{h^2 + k^2} + \frac{1 + h^2 + k^2}{h^2 + k^2}(hx_1 + kx_2)(hy_1 + ky_2) \\ &= \frac{(hx_1 + kx_2)(hy_1 + ky_2) + (kx_1 - hx_2)(ky_1 - hy_2)}{h^2 + k^2} \\ &\quad + (hx_1 + kx_2)(hy_1 + ky_2) \\ &= x_1y_1 + x_2y_2 + x_3y_3 = \mathcal{A}_1 \cdot \mathcal{A}_2. \end{aligned}$$

In conclusion, we find that

$$(50) \quad \|\mathcal{A}_1\| = \|\mathcal{A}_1\|, \quad \|\mathcal{A}_2\| = \|\mathcal{A}_2\| \quad \text{and} \quad \mathcal{A}_1 \cdot \mathcal{A}_2 = \mathcal{A}_1 \cdot \mathcal{A}_2.$$

By Remark 2.2, this means that $\mathcal{E}_P(O, V, W, O) = \mathcal{E}_P(OP_1, P_2, P_3)$. \square

Summing up from Lemmas 3.2, 3.3 and 3.4, we get:

Theorem 3.1. *Let us suppose that $OP_1 \not\parallel OP_2$. If $OP_3 = O$ then the segments OP_1, OP_2 are conjugate semi-diameters of the Pohlke's ellipse \mathcal{E}_P . Conversely, if $OP_3 \neq O$ then a pair of conjugate semi-diameters is given by the segments OV, OW with*

$$(51) \quad \overrightarrow{OV} = \pm \frac{k\overrightarrow{OP_1} - h\overrightarrow{OP_2}}{\sqrt{h^2 + k^2}} \quad \text{and} \quad \overrightarrow{OW} = \pm \sqrt{\frac{1 + h^2 + k^2}{h^2 + k^2}} \overrightarrow{OP_3},$$

where the coefficients h, k are such that

$$(52) \quad \overrightarrow{OP_3} = h\overrightarrow{OP_1} + k\overrightarrow{OP_2}.$$

With U_1, U_2, U_3 as in (38) we also have:

Lemma 3.5. *Let $\Phi : \omega \rightarrow \omega$ be the an affine transformation and let us suppose that*

$$(53) \quad OP_1 = \Phi(OU_1), \quad OP_2 = \Phi(OU_2), \quad OP_3 = \Phi(OU_3).$$

Then $\Phi(\mathcal{E}_P(O, U_1, U_2, U_3)) = \mathcal{E}_P(O, P_1, P_2, P_3)$.

Proof. From (53) it is clear that $OU_1 \not\parallel OU_2 \Rightarrow OP_1 \not\parallel OP_2$ and that

$$(54) \quad \overrightarrow{OU_3} = h\overrightarrow{OU_1} + k\overrightarrow{OU_2} \quad \Rightarrow \quad \overrightarrow{OP_3} = h\overrightarrow{OP_1} + k\overrightarrow{OP_2}.$$

If $U_3 = O$ then $P_3 = O$ and by the first part of Theorem 3.1, we know that

$$\mathcal{E}_P(O, U_1, U_2, O) \quad \text{and} \quad \mathcal{E}_P(O, P_1, P_2, O)$$

are determined by the pairs of conjugate semi-diameters (OU_1, OU_2) and (OP_1, OP_2) respectively. Since $OP_1 = \Phi(OU_1)$ and $OP_2 = \Phi(OU_2)$ it follows that

$$(55) \quad \Phi(\mathcal{E}_P(O, U_1, U_2, O)) = \mathcal{E}_P(O, P_1, P_2, O).$$

Conversely, by the second part of Theorem 3.1, if $U_3 \neq O$ then the ellipses $\mathcal{E}_P(O, U_1, U_2, U_3)$ and $\mathcal{E}_P(O, P_1, P_2, P_3)$ are determined by the pairs of conjugate semi-diameters $(O\Sigma_-, O\Sigma_+)$ (given by (39)) and (OV, OW) respectively. Since

$$(56) \quad \Phi(\overrightarrow{O\Sigma_-}) = \pm\overrightarrow{OV} \quad \text{and} \quad \Phi(\overrightarrow{O\Sigma_+}) = \pm\overrightarrow{OW},$$

we come to the same conclusion. \square

More generally, applying Lemma 3.5, we can easily prove the following:

Theorem 3.2. *Let $\Psi : \omega \rightarrow \omega$ be any affine transformation. Suppose the segments OP_1, OP_2, OP_3 are not all parallel and let \mathcal{E}_P be the corresponding Pohlke's ellipse. Then $\Psi(\mathcal{E}_P)$ is the Pohlke's ellipse corresponding to the triad of segments $\Psi(OP_1), \Psi(OP_2), \Psi(OP_3)$.*

Remark 3.4. *Suppose OP_1, OP_2, OP_3 are not all parallel and do not vanish. Let T_{ij} ($i \neq j$) be a point of contact of $\mathcal{E}_P(O, P_1, P_2, P_3)$ with \mathcal{E}_{P_i, P_j} . Let t_{ij} be the common tangent line at T_{ij} . Then we can easily show that*

$$(57) \quad t_{ij} \parallel OP_k \quad (k \neq i, j).$$

Indeed, by Lemma 3.3, if $OP_i \not\parallel OP_j$ it is sufficient to observe that the statement is true for the ellipses $\mathcal{E}_P(O, U_1, U_2, U_3)$ and \mathcal{E}_{U_1, U_2} . Conversely, if $OP_i \parallel OP_j$, taking $h \neq 0$ and $k = 0$ in (38), we note that the conclusion is true for $\mathcal{E}_P(O, U_1, U_2, U_3)$ and the degenerate ellipses \mathcal{E}_{U_1, U_3} , with $U_3 \neq O$

and $OU_1 \parallel OU_3$.¹ This result was first derived in [3, Theorem 2] through synthetic methods. \square

4. THE SECONDARY POHLKE'S ELLIPSE \mathcal{E}_S

In this section we suppose the segments OP_1, OP_2, OP_3 are non-parallel (i.e., $OP_i \not\parallel OP_j$ if $i \neq j$) and

$$(58) \quad \overrightarrow{OP_3} = h\overrightarrow{OP_1} + k\overrightarrow{OP_2}$$

with $h, k \neq 0$ such that

$$(59) \quad g(h, k) \stackrel{\text{def}}{=} h^4 + k^4 - 2h^2k^2 - 2h^2 - 2k^2 + 1 > 0.$$

By Theorem 1.1 there exists a unique secondary Pohlke's ellipse \mathcal{E}_S .⁴

As in the previous section we use a system of coordinate axes x, y, z such that ω is the plane $z = 0$ and (16) holds. Also we first consider the triad of segments OU_1, OU_2, OU_3 where

$$(60) \quad U_1 = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \quad U_2 = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} \quad \text{and} \quad U_3 = \begin{pmatrix} h \\ k \\ 0 \end{pmatrix} \quad \text{with} \quad h, k \neq 0$$

as above. Then, since OU_1, OU_2, OU_3 are non-parallel and

$$(61) \quad \overrightarrow{OU_3} = h\overrightarrow{OU_1} + k\overrightarrow{OU_2},$$

the secondary Pohlke's ellipse $\mathcal{E}_S(O, U_1, U_2, U_3)$ exists and it is unique. More precisely, from [6, Section 4], we know that the conditions (4), (5) and (6) (with $P_i = U_i$, for $1 \leq i \leq 3$) are verified by taking: \tilde{S} the sphere with center O and radius $\rho = 1$, the points

$$(62) \quad R_1 = U_1, \quad R_2 = U_2 \quad \text{and} \quad R_3 = \frac{1}{h^2 - k^2 + 1} \begin{pmatrix} 2h \\ 0 \\ \pm\sqrt{g(h, k)} \end{pmatrix},$$

where $g(h, k)$ is the function defined in (59).⁵ See formula (90) of [6]. This means that the direction of the projection $\tilde{\Pi}$ is given by the vector $\overrightarrow{R_3U_3}$. From these facts it follows that:

Lemma 4.1. *Suppose (59), (60) hold. Then the semi-axes of the secondary Pohlke's ellipse $\mathcal{E}_S(O, U_1, U_2, U_3)$ are represented by the segments $O\tilde{\Sigma}_-$ and $O\tilde{\Sigma}_+$ with*

$$(63) \quad \tilde{\Sigma}_- = \frac{\pm 1}{\sqrt{H^2 + K^2}} \begin{pmatrix} K \\ -H \\ 0 \end{pmatrix}, \quad \tilde{\Sigma}_+ = \pm \sqrt{\frac{g + H^2 + K^2}{g(H^2 + K^2)}} \begin{pmatrix} H \\ K \\ 0 \end{pmatrix}$$

⁴ Condition (58)-(59) is clearly equivalent to (8)-(9). But (58)-(59) allows us to obtain slight simpler expressions.

⁵ Note that condition (59) $\Rightarrow h^2 - k^2 \neq \pm 1$. In fact, since $g(h, k) = (h^2 - k^2)^2 - 2h^2 - 2k^2 + 1$, we get

$$h^2 - k^2 = \pm 1 \quad \Rightarrow \quad g(h, k) = 2(1 - h^2 - k^2) = \begin{cases} -4h^2 & \text{if } h^2 - k^2 = -1 \\ -4k^2 & \text{if } h^2 - k^2 = 1 \end{cases}.$$

where $g = g(h, k)$ and

$$(64) \quad H \stackrel{\text{def}}{=} h(h^2 - k^2 - 1), \quad K \stackrel{\text{def}}{=} k(h^2 - k^2 + 1).$$

Proof. From (62) we have

$$(65) \quad \overrightarrow{R_3 U_3} = \frac{1}{h^2 - k^2 + 1} \begin{pmatrix} h(h^2 - k^2 - 1) \\ k(h^2 - k^2 + 1) \\ \mp \sqrt{g(h, k)} \end{pmatrix}.$$

Thus multiplying the right hand side of (65) by the factor $\frac{h^2 - k^2 + 1}{\sqrt{g(h, k)}}$ we see that the direction of projection is given by the vector

$$(66) \quad \vec{w} = \begin{pmatrix} -H/\sqrt{g} \\ -K/\sqrt{g} \\ 1 \end{pmatrix} \quad \text{or} \quad \begin{pmatrix} H/\sqrt{g} \\ K/\sqrt{g} \\ 1 \end{pmatrix},$$

where the terms H, K are defined as in (64). Furthermore $H, K \neq 0$ because $h, k \neq 0$ and condition (59) holds.⁵ Then, taking into account that the sphere \tilde{S} has center O and radius $\rho = 1$ we easily get (63). \square

Corollary 4.1. *Suppose (59), (60) hold. Then*

$$(67) \quad \text{area}(\mathcal{E}_P(O, U_1, U_2, U_3)) < \text{area}(\mathcal{E}_S(O, U_1, U_2, U_3)).$$

Proof. From the expressions (39) and (63) we have $|O\Sigma_-| = |O\tilde{\Sigma}_-| = 1$. Thus it is enough to prove the inequality $|O\Sigma_+|^2 < |O\tilde{\Sigma}_+|^2$, that is

$$(68) \quad 1 + h^2 + k^2 < \frac{g + H^2 + K^2}{g}.$$

Since we know that $g > 0$, (68) is equivalent to $(h^2 + k^2)g < H^2 + K^2$. Introducing the expressions (59) and (64), with elementary calculations the last inequality reduces to

$$(69) \quad 0 < h^2 k^2,$$

which is clearly verified because we are assuming $h, k \neq 0$. \square

We can now give the expressions of a pair of conjugate semi-diameters of the secondary Pohlke's ellipse $\mathcal{E}_S(O, P_1, P_2, P_3)$. Indeed, with U_1, U_2, U_3 as in (60), we have:

Lemma 4.2. *Suppose the segments OP_1, OP_2, OP_3 are non-parallel and condition (58)-(59) (or (8)-(9)) holds. Let $\Phi : \omega \rightarrow \omega$ be the affine transformation such that $OP_1 = \Phi(OU_1)$, $OP_2 = \Phi(OU_2)$. Then*

$$(70) \quad \Phi(\mathcal{E}_S(O, U_1, U_2, U_3)) = \mathcal{E}_S(O, P_1, P_2, P_3).$$

In particular the segments $O\tilde{V}$ and $O\tilde{W}$, with

$$(71) \quad \begin{aligned} \overrightarrow{O\tilde{V}} &= \pm \frac{K \overrightarrow{OP_1} - H \overrightarrow{OP_2}}{\sqrt{H^2 + K^2}}, \\ \overrightarrow{O\tilde{W}} &= \pm \sqrt{\frac{g + H^2 + K^2}{g(H^2 + K^2)}} \left(H \overrightarrow{OP_1} + K \overrightarrow{OP_2} \right), \end{aligned}$$

are conjugate semi-diameters of $\mathcal{E}_S(O, P_1, P_2, P_3)$.

Proof. In view of Pohlke's theorem and Theorem 1.1, there are exactly two distinct ellipses with center O and circumscribing \mathcal{E}_{P_1, P_2} , \mathcal{E}_{P_2, P_3} , \mathcal{E}_{P_3, P_1} . Namely, the Pohlke's ellipse $\mathcal{E}_P(O, P_1, P_2, P_3)$ and the secondary Pohlke's ellipse $\mathcal{E}_S(O, P_1, P_2, P_3)$. Noting that $\Phi(OU_3) = OP_3$, we have

$$(72) \quad \Phi(\mathcal{E}_{U_1, U_2}) = \mathcal{E}_{P_1, P_2}, \quad \Phi(\mathcal{E}_{U_2, U_3}) = \mathcal{E}_{P_2, P_3}, \quad \Phi(\mathcal{E}_{U_3, U_1}) = \mathcal{E}_{P_3, P_1}.$$

Since the ellipse $\mathcal{E}_S(O, U_1, U_2, U_3)$ circumscribes \mathcal{E}_{U_1, U_2} , \mathcal{E}_{U_2, U_3} and \mathcal{E}_{U_3, U_1} , we deduce that

$$(73) \quad \Phi(\mathcal{E}_S(O, U_1, U_2, U_3)) \text{ circumscribes } \mathcal{E}_{P_1, P_2}, \mathcal{E}_{P_2, P_3}, \mathcal{E}_{P_3, P_1}.$$

By Lemma 3.5 we know that $\Phi(\mathcal{E}_P(O, U_1, U_2, U_3)) = \mathcal{E}_P(O, P_1, P_2, P_3)$, thus we must conclude that

$$(74) \quad \Phi(\mathcal{E}_S(O, U_1, U_2, U_3)) = \mathcal{E}_S(O, P_1, P_2, P_3)$$

because $\mathcal{E}_S(O, U_1, U_2, U_3) \neq \mathcal{E}_P(O, U_1, U_2, U_3)$.

Finally, taking account Lemma 4.1, we see that the segments $\Phi(O\tilde{\Sigma}_-)$ and $\Phi(O\tilde{\Sigma}_+)$ are conjugate semi-diameters of $\Phi(\mathcal{E}_S(O, U_1, U_2, U_3))$, hence the segments $O\tilde{V}, O\tilde{W}$ given by (71) are conjugate semi-diameters of the secondary Pohlke's ellipse $\mathcal{E}_S(O, P_1, P_2, P_3)$. \square

From Corollary 4.1 and Lemma 4.2 it is now clear that:

Corollary 4.2. *Suppose the segments OP_1, OP_2, OP_3 are non-parallel and condition (58)-(59) (i.e., (8)-(9)) holds. Then*

$$(75) \quad \text{area}(\mathcal{E}_P(O, P_1, P_2, P_3)) < \text{area}(\mathcal{E}_S(O, P_1, P_2, P_3)).$$

More generally, if $\Psi : \omega \rightarrow \omega$ is any affine transformation of the plane ω , applying the previous results we can easily prove the following:

Theorem 4.1. *Suppose the segments OP_1, OP_2, OP_3 are non-parallel and condition (8)-(9) holds. Let \mathcal{E}_S be the secondary Pohlke's ellipse of the triad OP_1, OP_2, OP_3 . Then $\Psi(\mathcal{E}_S)$ is the secondary Pohlke's ellipse of the triad of segments $\Psi(OP_1), \Psi(OP_2), \Psi(OP_3)$.*

5. A DETERMINATION OF THE SECONDARY POHLKE'S PROJECTION

In this section we give formulae for determining the secondary Pohlke's projection of a triad of non-parallel segments OP_1, OP_2, OP_3 satisfying the condition (8)-(9). That is a parallel projection $\tilde{\Pi} : \mathbb{E}^3 \rightarrow \omega$, a sphere \tilde{S} with center O and three points $R_1, R_2, R_3 \in \tilde{S}$ such that (4), (5), (6) hold.

We already know that \tilde{S} is unique, $\tilde{\Pi}$ is unique up to symmetry with respect to ω , and that the set $\{R_1, R_2, R_3\}$ is determined up to symmetry with respect to ω and up to symmetry with respect to a plane $\tilde{\pi}$ through O and perpendicular to the direction of projection. See Remark 2.1 and [6].

To begin with, we note the following:

Claim 5.1. *Let $\tilde{\Pi} : \mathbb{E}^3 \rightarrow \omega$ be a secondary Pohlke's projection for OP_1, OP_2, OP_3 and suppose the nonzero vector \vec{w} represents the direction of this projection. Then the following hold:*

$$(a) \quad OR_i, OR'_i \not\perp \vec{w} \quad (1 \leq i \leq 3).$$

(b) If the vector \vec{w} is known, then the points $R_1, R_2, R_3, R'_1, R'_2, R'_3$ can be recursively computed from any of them. For example, if R_3 is given then we immediately have:

$$(76) \quad \overrightarrow{OR_2} = \overrightarrow{OP_2} - \frac{\overrightarrow{OR_3} \cdot \overrightarrow{OP_2}}{\overrightarrow{OR_3} \cdot \vec{w}} \vec{w}, \quad \overrightarrow{OR'_1} = \overrightarrow{OP_1} - \frac{\overrightarrow{OR_3} \cdot \overrightarrow{OP_1}}{\overrightarrow{OR_3} \cdot \vec{w}} \vec{w}.$$

Proof. (a) It follows from condition (6). Indeed, if $OR_i \perp \vec{w}$, or if $OR'_i \perp \vec{w}$, then $R_i = R'_i \in \tilde{\pi}$ where $\tilde{\pi}$ is the plane through O and perpendicular to \vec{w} . Thus (6) fails.

(b) By condition (4) we have $\tilde{\Pi}(R_2) = P_2$, thus $\overrightarrow{OR_2} = \overrightarrow{OP_2} + t\vec{w}$ for some $t \in \mathbb{R}$. By (5) we also know that $OR_2 \perp OR_3$. So, taking account that $\overrightarrow{OR_3} \cdot \vec{w} \neq 0$, we obtain

$$(77) \quad t = -\frac{\overrightarrow{OR_3} \cdot \overrightarrow{OP_2}}{\overrightarrow{OR_3} \cdot \vec{w}}.$$

This gives the first equality of (76). Noting that $\tilde{\Pi}(R'_1) = P_1$ and $OR_3 \perp OR'_1$, in the same way we can derive the second equality. To conclude it is enough to consider also the points R'_2 and R'_3 , because from condition (5) we get a cyclic relation of orthogonality:

$$(78) \quad \begin{aligned} OR_1 \perp OR_2, \quad OR_2 \perp OR_3, \quad OR_3 \perp OR'_1, \\ OR'_1 \perp OR'_2, \quad OR'_2 \perp OR'_3, \quad OR'_3 \perp OR_1. \end{aligned}$$

So we can start from any point of the set $\{R_1, R_2, R_3, R'_1, R'_2, R'_3\}$. \square

Next, suppose that the segments OP_1, OP_2, OP_3 are non-parallel and that the condition (58)-(59) (i.e., (8)-(9)) is true. By Theorem 2.1 of [6] there exist a sphere \tilde{S} with center O , three point $R_1, R_2, R_3 \in \tilde{S}$ and a parallel projection $\tilde{\Pi} : \mathbb{E}^3 \rightarrow \omega$ such that the conditions (4), (5), (6) hold. To determine R_1, R_2, R_3 and $\tilde{\Pi}$, we begin by observing that setting

$$(79) \quad \overrightarrow{OX_3} = \frac{H}{\sqrt{g}} \overrightarrow{OP_1} + \frac{K}{\sqrt{g}} \overrightarrow{OP_2},$$

we have

$$(80) \quad \mathcal{E}_S(O, P_1, P_2, P_3) = \mathcal{E}_P(O, P_1, P_2, X_3).$$

Indeed, by Lemma 3.4 the segments $O\widehat{V}$ and $O\widehat{W}$, with

$$(81) \quad \overrightarrow{O\widehat{V}} = \pm \frac{\frac{K}{\sqrt{g}} \overrightarrow{OP_1} - \frac{H}{\sqrt{g}} \overrightarrow{OP_2}}{\sqrt{\frac{H^2}{g} + \frac{K^2}{g}}} \quad \text{and}$$

$$(82) \quad \overrightarrow{O\widehat{W}} = \pm \sqrt{\frac{1 + \frac{H^2}{g} + \frac{K^2}{g}}{\frac{H^2}{g} + \frac{K^2}{g}}} \left(\frac{H}{\sqrt{g}} \overrightarrow{OP_1} + \frac{K}{\sqrt{g}} \overrightarrow{OP_2} \right),$$

are conjugate semi-diameters of the Pohlke's ellipse $\mathcal{E}_P(O, P_1, P_2, X_3)$. Noting the expressions (71) of Lemma 4.2, it is clear $O\widehat{V}, O\widehat{W}$ coincide with the conjugate semi-diameters $O\widetilde{V}, O\widetilde{W}$ respectively of the secondary Pohlke's ellipse $\mathcal{E}_S(O, P_1, P_2, P_3)$. Thus (80) holds.

Thanks to the considerations made in Remark 2.1, this implies that the secondary Pohlke's projection $\tilde{\Pi}$ corresponding to the triad of segments OP_1, OP_2, OP_3 and the Pohlke's projection of the triad OP_1, OP_2, OX_3 are equal. More precisely, taking account the conditions (1) and (2), let us denote with \hat{S} a sphere centered at O , with $\hat{Q}_1, \hat{Q}_2, \hat{Q}_3$ three points of \hat{S} and with $\hat{\Pi} : \mathbb{E}^3 \rightarrow \omega$ a parallel projection such that:

$$(83) \quad \hat{\Pi}(O\hat{Q}_1) = OP_1, \quad \hat{\Pi}(O\hat{Q}_2) = OP_2 \quad \text{and} \quad \hat{\Pi}(O\hat{Q}_3) = OX_3,$$

$$(84) \quad O\hat{Q}_1 \perp O\hat{Q}_2, \quad O\hat{Q}_2 \perp O\hat{Q}_3, \quad O\hat{Q}_3 \perp O\hat{Q}_1.$$

Then, by Remark 2.1, it follows that

$$(85) \quad \tilde{S} = \hat{S} \quad \text{and} \quad \tilde{\Pi} \sim \hat{\Pi}.$$

For our purposes the projection $\tilde{\Pi}$ and its symmetric with respect to the plane ω are equivalent, thus we can take $\tilde{\Pi} = \hat{\Pi}$. Then, to fulfill the conditions (4), (5) and (6), we only need only to select appropriately the points $R_1, R_2, R_3 \in \hat{S}$. More precisely,

$$(86) \quad R_i = \hat{Q}_i \quad \text{or} \quad R_i = \hat{Q}_i' \quad (1 \leq i \leq 2)^6$$

and then $R_3 \in \hat{S}$ such that

$$(87) \quad \hat{\Pi}(R_3) = P_3 \quad \text{and} \quad OR_3 \perp OR_1'.$$

Thanks to the symmetry with respect to the plane $\hat{\pi}$, it is indifferent to start with $R_1 = \hat{Q}_1$ or $R_1 = \hat{Q}_1'$. If, for instance, we start with $R_1 = \hat{Q}_1$ then we must take

$$(88) \quad R_2 = \hat{Q}_2,$$

because $O\hat{Q}_1 \not\perp O\hat{Q}_2'$.⁷ After selecting R_2 , the point R_3 can be obtained by applying Claim 5.1. Namely, we must have

$$(89) \quad \overrightarrow{OR_3} \stackrel{\text{def}}{=} \overrightarrow{OP_3} - \frac{\overrightarrow{OR_2} \cdot \overrightarrow{OP_3}}{\overrightarrow{OR_2} \cdot \vec{w}} \vec{w},$$

where \vec{w} is any nonzero vector representing the direction of the secondary Pohlke's projection $\tilde{\Pi}$, i.e., the direction of the projection $\hat{\Pi}$.

5.1. Reference tetrahedron and direction of projection. Summarizing up we give now a procedure for determining the points R_1, R_2, R_3 and the direction of the secondary Pohlke's projection. As for Pohlke's projection, we use a system of coordinate axes x, y, z such that ω is the plane

⁶ Because $\hat{\Pi}(\hat{Q}_i) = \hat{\Pi}(\hat{Q}_i') = P_i$, for $1 \leq i \leq 2$. According to the previous notation, \hat{Q}_i' is symmetric to \hat{Q}_i with respect to the plane $\hat{\pi}$ through O and perpendicular to the direction of the projection $\hat{\Pi}$.

⁷ Indeed, $O\hat{Q}_1 \perp O\hat{Q}_2 \wedge O\hat{Q}_1 \perp O\hat{Q}_2' \Rightarrow \hat{Q}_1 \in \hat{\pi} \vee \hat{Q}_2 \in \hat{\pi}$. But this cannot happen because, by (85), we already know that $\tilde{\Pi} = \hat{\Pi}$ is as secondary Pohlke's projection for the triad of segments OP_1, OP_2, OP_3 .

$z = 0$ and (16) holds. We suppose that OP_1, OP_2, OP_3 are non-parallel and that condition (58)-(59) is true. Then we consider the matrix

$$(90) \quad \widehat{A} = \begin{pmatrix} x_1 & x_2 & \widehat{x}_3 \\ y_1 & y_2 & \widehat{y}_3 \\ 0 & 0 & 0 \end{pmatrix} = \begin{pmatrix} \widehat{A}_1 \\ \widehat{A}_2 \\ 0 \end{pmatrix},$$

where

$$(91) \quad \widehat{x}_3 = \frac{H}{\sqrt{g}} x_1 + \frac{K}{\sqrt{g}} x_2, \quad \widehat{y}_3 = \frac{H}{\sqrt{g}} y_1 + \frac{K}{\sqrt{g}} y_2$$

and $H = h(h^2 - k^2 - 1)$, $K = k(h^2 - k^2 + 1)$ are the terms introduced in (64) with h, k as in (58). Having defined the matrix \widehat{A} , we continue by following the formulae (3.6), (3.10), (3.21), (3.22) of [4]. We define the quantities:

$$(92) \quad \widehat{\gamma} = \arccos \left(\frac{\widehat{A}_1 \cdot \widehat{A}_2}{\|\widehat{A}_1\| \|\widehat{A}_2\|} \right), \quad \widehat{\lambda} = \frac{\|\widehat{A}_1\|}{\|\widehat{A}_2\|},$$

$$(93) \quad \widehat{\eta} = \frac{\widehat{\lambda}^2 + 1 + \sqrt{(\widehat{\lambda}^2 + 1)^2 - 4\widehat{\lambda}^2 \sin^2 \widehat{\gamma}}}{2\widehat{\lambda}^2 \sin^2 \widehat{\gamma}},$$

$$(94) \quad \widehat{\nu} = \pm \widehat{\rho} \quad \text{with} \quad \widehat{\rho} = \frac{\|\widehat{A}_1\|}{\widehat{\lambda} \sqrt{\widehat{\eta}}} = \frac{\|\widehat{A}_2\|}{\sqrt{\widehat{\eta}}},$$

and, finally,

$$(95) \quad (\widehat{\alpha}, \widehat{\beta}) = \pm \left(\sqrt{\widehat{\eta} \widehat{\lambda}^2 - 1}, \operatorname{sgn}(\cos \widehat{\gamma}) \sqrt{\widehat{\eta} - 1} \right),$$

where $t \mapsto \operatorname{sgn}(t)$ is the ‘‘signum’’ function introduced in (21). Then, by the results of [4, Section 4], the coordinates of the points $\widehat{Q}_1, \widehat{Q}_2, \widehat{Q}_3$ satisfying (83), (84) are the columns $\widehat{B}^1, \widehat{B}^2, \widehat{B}^3$ respectively of the matrix

$$(96) \quad \widehat{B} = \frac{1}{1 + \widehat{\alpha}^2 + \widehat{\beta}^2} \begin{pmatrix} 1 + \widehat{\beta}^2 & -\widehat{\alpha} \widehat{\beta} & -\widehat{\alpha} \\ -\widehat{\alpha} \widehat{\beta} & 1 + \widehat{\alpha}^2 & -\widehat{\beta} \\ \widehat{\alpha} & \widehat{\beta} & 1 \end{pmatrix} \cdot \begin{pmatrix} x_1 & x_2 & \widehat{x}_3 \\ y_1 & y_2 & \widehat{y}_3 \\ \frac{x_2 \widehat{y}_3 - y_2 \widehat{x}_3}{\widehat{\nu}} & \frac{y_1 \widehat{x}_3 - x_1 \widehat{y}_3}{\widehat{\nu}} & \frac{x_1 y_2 - y_1 x_2}{\widehat{\nu}} \end{pmatrix}.$$

The direction of the projection $\widehat{\Pi} : \mathbb{E}^3 \rightarrow \omega$ is determined by the vector

$$(97) \quad \vec{w} = \begin{pmatrix} -\widehat{\alpha} \\ -\widehat{\beta} \\ 1 \end{pmatrix}.$$

Recalling the arguments from (86) to (89), it is now sufficient to modify the third column of $\widehat{B} = (\widehat{B}^1, \widehat{B}^2, \widehat{B}^3)$. More precisely, we define the matrix $\widetilde{B} = (\widetilde{B}^1, \widetilde{B}^2, \widetilde{B}^3)$ by setting

$$(98) \quad \widetilde{B}^1 = \widehat{B}^1, \quad \widetilde{B}^2 = \widehat{B}^2 \quad \text{and} \quad \widetilde{B}^3 = P_3 - \frac{\widehat{B}^2 \cdot P_3}{\widehat{B}^2 \cdot \vec{w}} \vec{w}.$$

The coordinates of the points R_1, R_2, R_3 are then the columns $\tilde{B}^1, \tilde{B}^2, \tilde{B}^3$ respectively and the direction of the secondary Pohlke's projection $\tilde{\Pi}$ is represented by \vec{w} defined in (97), so we have

$$(99) \quad \tilde{\Pi} \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} x + \hat{\alpha}z \\ y + \hat{\beta}z \\ 0 \end{pmatrix}.$$

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